Oscillations all derivations

A body executing SHM can be compared with a body doing circular motion having radius A as shown. Let this body covers an angle θ in time after starting from X (A,0) at t = 0.

$$\frac{y}{A} = \sin\theta$$
$$\therefore y = A\sin\omega t$$

This is the displacement equation of a body amplitude of whose motion is A and angular frequency is ω

Velocity in SHM

$$v = \frac{dy}{dt} = A\omega cos\omega t$$

$$\Rightarrow v = A\omega \sqrt{1 - sin^2 \omega t}$$

$$\Rightarrow v = A\omega \sqrt{1 - \frac{y^2}{A^2}}$$

$$\Rightarrow v = A\omega \frac{\sqrt{A^2 - y^2}}{A}$$

$$\Rightarrow v = \omega \sqrt{A^2 - y^2}$$

 $v_{max} = A\omega$

Acceleration in SHM

$$a = \frac{dv}{dt} = \frac{d}{dt} (A\omega \cos \omega t)$$
$$\Rightarrow a = -A\omega^{2} \sin \omega t$$
$$\Rightarrow \boxed{a = -\omega^{2}y} \qquad \dots \dots (i)$$

Restoring force

$$F = ma$$

 $\Rightarrow F = -m\omega^2 y$

Time period in SHM

 \therefore F = -ky and also F = -m ω^2 y $\therefore k = m\omega^2$





So,
$$\omega = \sqrt{\frac{k}{m}}$$

or $\frac{2\pi}{T} = \sqrt{\frac{k}{m}}$
 $\Rightarrow T = 2\pi \sqrt{\frac{m}{k}}$

Also, from i

$$\Rightarrow \left[T = 2\pi \sqrt{\frac{m}{k}} \right]$$
Also, from i

$$\omega = \sqrt{\frac{a}{y}}$$

$$\Rightarrow \frac{2\pi}{T} = \sqrt{\frac{a}{y}}$$

$$\Rightarrow T = 2\pi \sqrt{\frac{y}{a}} = 2\pi \sqrt{\frac{\text{acceleration}}{\text{displacement}}}$$
Kinetic energy in SHM

$$KE = \frac{1}{2}mv^{2}$$

$$\Rightarrow KE = \frac{1}{2}m(\omega\sqrt{A^{2} - y^{2}})^{2}$$

$$\Rightarrow \left[KE = \frac{1}{2}m\omega^{2}A^{2} - \frac{1}{2}m\omega^{2}y^{2} \right]$$
Potential energy in SHM

$$PE = \frac{1}{2}ky^{2}$$

Kinetic energy in SHM

$$KE = \frac{1}{2}mv^{2}$$
$$\Rightarrow KE = \frac{1}{2}m\left(\omega\sqrt{A^{2} - y^{2}}\right)^{2}$$
$$\Rightarrow KE = \frac{1}{2}m\omega^{2}A^{2} - \frac{1}{2}m\omega^{2}y^{2}$$

Potential energy in SHM

$$PE = \frac{1}{2}ky^{2}$$
$$\Rightarrow PE = \frac{1}{2}m\omega^{2}y^{2}$$

Total energy in SHM

$$TE = PE + KE$$

$$\Rightarrow TE = \frac{1}{2}m\omega^{2}y^{2} + \frac{1}{2}m\omega^{2}A^{2} - \frac{1}{2}m\omega^{2}y^{2}$$

$$\Rightarrow TE = \frac{1}{2}m\omega^{2}A^{2}$$

Time period of simple pendulum

Consider a pendulum of length L connected to a bob of mass m as shown. Now from figure it is clear that $mgsin\theta$ provides the necessary restoring force. Therefore

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In this spring mass system shown in figure above, time period of oscillation is given by

$$T=2\pi\sqrt{\frac{m}{k}}$$

Vertical spring

When a block is connected to a vertical spring, it extends by an amount ℓ so that the restoring force balances the weight of the block. Therefore,

 $mg = k\ell$

So,
$$k = \frac{mg}{\ell}$$





$$mg = k\ell$$

So, k = $\frac{mg}{\ell}$

Now, when this spring is pulled by a distance y, it starts doing SHM with time period T which is given by

$$\therefore T = 2\pi \sqrt{\frac{m\ell}{mg}}$$
$$T = 2\pi \sqrt{\frac{\ell}{g}}$$

Combination of springs

Series combination

Consider two springs of spring constants k_1 and k_2 connected in series as shown. Now, when this system oscillates, extensions in springs be y_1 and y_2 , then

$$F = -k_1y_1 = -k_2y_2$$

Total extension is

$$y = y_1 + y_2$$

$$\Rightarrow y = -\frac{F}{k_1} - \frac{F}{k_1}$$

$$\Rightarrow y = -F\left(\frac{1}{k_1} + \frac{1}{k_2}\right)$$

$$\Rightarrow F = -\left(\frac{k_1k_2}{k_1 + k_2}\right)y$$
Comparing it with F = -kx, we get

$$k = \frac{k_1k_2}{k_1 + k_2}$$
which gives

$$\frac{1}{k} = \frac{1}{k_1} + \frac{1}{k_2}$$

$$\therefore T = 2\pi \sqrt{\frac{m(k_1 + k_2)}{k_1k_2}}$$



Parallel combination

Consider two springs of spring constants k_1 and k_2 connected in series as shown. Now, when this system oscillates, extensions in springs be y and restoring forces be F_1 and F_2 , then





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